

CLEVELAND ALLIANCES LTD INDUSTRY AGRICULTURE AMENITY



# **GOLF** BRAVO 1805 SERIES COMPUTER

CE

Software rel. 1.6.x

**INSTALLATION, USE AND MAINTENANCE** 

# **LEGEND OF SYMBOLS**



=	Indications for crop SPRAYERS
=	Indications for multi-row SPRAYERS
=	Indications for ORCHARD SPRAYERS

This manual is an integral part of the equipment to which it refers and must accompany the equipment in case of sale or change of ownership. Keep it for any future reference; ARAG reserves the right to modify product specifications and instructions at any moment and without notice.

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# MANUAL FOREWORD AND USE

This manual provides instructions to assemble, connect and set the computers of the BRAVO 180S family. Any other information is provided in specific sheets to be used exclusively by the installer, containing specific information of each computer model.

### MANUAL USE MODES

The section of this manual dedicated to the installation contains information for installers. For this reason we have used technical terms without providing explanations which would be necessary for end users only.

THE INSTALLATION MUST BE CARRIED OUT BY AUTHORISED AND SKILLED PERSONNEL ONLY. THE MANUFACTURER IS NOT RESPONSIBLE FOR ANY OPERATION SPECIFIED IN THIS MANUAL CARRIED OUT BY UNAUTHORISED OR UNSKILLED PERSONNEL.

## LIMITATIONS

The descriptions of the assembly phases refer to a "general" computer, so specific models will not be mentioned, unless a certain installation procedure concerns exclusively one computer type.

### RESPONSIBILITY

The installer must carry out workmanlike installations and ensure to the end user the perfect operation of the whole system both with ARAG components only and other brands' components.

ARAG always recommends using its components to install control systems.

The installer will be held responsible for any malfunction if he decides to use other brands' components even without actually changing the system parts or harness.

The compatibility check with components and accessories of other manufacturers shall be carried out by the installer.

If the computer or the ARAG components installed together with other brands' components get damaged because of what stated above, no direct or indirect warranty will be provided.

# **1 PRODUCT DESCRIPTION**

The device you have purchased is a computer which, when connected to a valve or suitable control unit, makes it possible to control all phases of treatment in agricultural applications directly from the cabin of the farming machine it is installed in.

These computers can be connected to different sensor types.

The computer is directly connected to the system by means of two cables connected to the hydraulic and control unit valves and the sensors. In the cabin you find all controls necessary to manage the system ensuring great safety during the job.

The BRAVO 18x computer display allows the operator to constantly monitor all data of the current operations, such as vehicle speed, sprayed fluid quantity, the whole sprayed area and so on.

# 2 BRAVO DSB

ARAG has designed and manufactured a diagnostics system for Bravo series computers and the systems they may be connected to. BRAVO DSB (code 467003) provides reliable diagnostics of computer, control unit or the whole system troubleshooting any potential problems experienced with the BRAVO DSB system.

# 3 RISKS AND PROTECTIONS BEFORE ASSEMBLY

All installation works must be done with battery disconnected, using suitable tools and any individual protection equipment deemed necessary.

 $\Delta$  Use ONLY clean water for treatment tests and simulations: using chemicals during simulated treatment runs can seriously injure persons in the vicinity.

# INTENDED USE

This device is designed to work on agricultural machinery for spraying and crop spraying applications.

The machine is designed and built in compliance with UNI EN ISO 14982 standard (Electromagnetic compatibility - Forestry and farming machines), harmonized with 2004/108/EC Directive.

# PRECAUTIONS

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• Do not aim water jets at the equipment.

- Do not use solvents or fuel to clean the case outer surface.
- Do not clean equipment with direct water jets.
- Comply with the specified power voltage (12 VDC).
- In case of voltaic arc welding, remove connectors from BRAVO and disconnect the power cables.
- Only use ARAG genuine spare parts and accessories.

6

# PACKAGE CONTENT

The table below indicates the components that you will find in the BRAVO computer package:





# 7 POSITION ON FARMING MACHINE

# 7.1 System recommended composition





The computer must be directly connected to the farming machine battery. \* Do not connect the computer to key-operated switch (15/54).

# INSTALLATION



The computer must be directly connected to the farming machine battery. \* Do not connect the computer to key-operated switch (15/54).

8

# 7.2 Computer positioning

• The BRAVO 180S series computer must be placed in the control cabin of the farming machine. Observe the following precautions:

\_\_\_\_\_\_ - Do

- Do NOT install the monitor in areas where it would be subjected to excessive vibrations or shocks, to prevent any damage or

accidental use of the control keys;

- Install the device in a visible position within easy reach by hand; bear in mind that the monitor should not obstruct the operator's freedom of movement or block his view.

Consider all necessary connections of the computer, the cable length, and make sure there is enough space for connectors and cables.

An identification symbol is located next to each connector to indicate its function. For any reference to the system configuration read par. 7.1 System recommended composition.





ITEM	CONNECTION POINTS
1	Control unit and sensors
2	Hydraulic unit
3	Power supply
4	Auxiliary connections
5	USB

SECTIONS	MASTER	PRESSURE	WIDTH A (mm)			
	•	•	152			
2	•	•	152			
3	•	•	152			
4	•	•	222			
5	•	•	222			
7	•	•	268			

# 7.3 Bracket fixing

The monitor must be mounted after having fixed the bracket at the desired location (the previous paragraph shows the bracket drilling template). The bracket must be slid out of the monitor seat (A, Fig. 8) and fixed using the supplied screws (B). Make sure the bracket is securely mounted, fit the monitor on it, and push it until it locks in place (C).



### 7.4 Control unit position

The control unit must be fixed with the special brackets supplied and fitted to the unit, positioning it as shown in the manual provided with the assembly. MAKE SURE TO FOLLOW ALL THE SAFETY INSTRUCTIONS GIVEN IN THE CONTROL UNIT'S MANUAL.

### 7.5 Hydraulic unit positioning

The hydraulic unit shall be secured to the machine, making sure it is well protected against the elements and the fluid sprayed by the machine.

ARAG IS NOT LIABLE FOR ANY DAMAGE RESULTING FROM THE INSTALLATION BY UNSKILLED PERSONNEL. ANY SYSTEM DAMAGE CAUSED BY A WRONG INSTALLATION AND/OR CONNECTION AUTOMATICALLY VOIDS THE WARRANTY.

WARNING! DO NOT CONNECT HYDRAULIC UNITS OTHER THAN THE SPECIFIED ONES (SEE ARAG GENERAL CATALOGUE). ARAG IS NOT LIABLE FOR ANY DAMAGE TO THE PRODUCT, MALFUNCTION ERRORS AND ANY KIND OF RISK IF THE MODULE IS CONNECTED TO NON ORIGINAL UNITS OR UNITS NOT SUPPLIED BY ARAG.



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# 8 COMPUTER CONNECTION TO THE FARMING MACHINE

# 8.1 General precautions for a correct harness position

- Securing the cables:
- secure the harness so that it does not interfere with moving parts;
- route the harnesses so that they cannot be damaged or broken by machine movements or twisting.

### • Routing the cables to protect against water infiltrations:

- the cable branches must ALWAYS be faced downwards (see figures below).



• Fitting the cables to the connection points:

- do not force the connectors by pushing too hard or bending them: the contacts may be damaged and computer operation may be compromised.

Use ONLY the cables and accessories indicated in the catalogue, having technical features suitable for the use to be made of them.

# 8.2 Power supply connection

The package includes the power connector (Fig. 1 and Fig. 2 on page 6) to be connected to the farming machine battery; Fig. 13 shows the drilling template of the power connector.

Connect the power connector to the battery wires using two 6-mm faston connectors, as indicated in Fig. 11 and Fig. 12. Use the cable provided with the package (Fig. 1 and Fig. 2 on page 6) to connect the computer to the power supply.



### WARNING:

# To avoid short circuits, do not connect the power cables to battery before the installation is completed.

Before powering up the computer and control unit, make sure the battery voltage is as specified (12 Vdc). BRAVO 180S is supplied directly by the farming machine battery (12 Vdc): ALWAYS switch on the computer through the monitor, and then remember to switch it off using the specific key on the control panel.

# M

If BRAVO 180S remains on for a long time with the machine off, the tractor battery could run flat: in case of prolonged breaks of the machine with engine off, make sure the computer is off, too.

The power source must be connected as indicated in Fig. 14: the computer must be connected directly to the farming machine battery. DO NOT connect the computer to key-operated switch (15/54).



# WARNING:

• The power circuit shall ALWAYS be protected by a 10 A fuse like the ones for automotive applications.

• All cables connected to the battery shall have a minimum crosssection of 2.5 sq. mm.

To avoid short-circuits, connect the power cable connector only after completing installation.

• Use cables with suitable terminals ensuring correct connection of all wires.





Fix the connectors to the relevant valves according to the initials indicated in your assembly general diagram (7.1 System recommended composition): • Remove the protection cap (1, Fig. 16) from the electric valve.

Place the seal (2) onto the connector (3), and push the connector fully on (4): be careful not to bend the contacts upon insertion on the valve.
Tighten the screw (5) fully home.

In case there are more monitor switches than section valves, connect the cables as indicated in the table:

SECTION VALVE NO.	SWITCHES TO BE USED	CABLES TO BE CONNECTED TO THE SECTION VALVES	
2	2 - 4	2 - 4	
3	2 - 3 - 4	2 - 3 - 4	
4	1 - 2 - 4 - 5	1 - 2 - 4 - 5	

#### 9.3 Hydraulic valve connection

4	
	`
3	/
	)
RAND	
Fig. 24	

η.

Boom locking

Boom leveling 

Bravo 180S can control up to 7 hydraulic functions through double-acting valves.

Fix the connectors to the relevant valves according to the initials indicated in your assembly general diagram (7.1 System recommended composition).

AC

BA

вс

CA

CC

• Position seal (1) onto connector (2), then connect the latter pressing it fully home (3): during this operation, take special care not to bend valve electric contacts. • Insert screw inside connector, and screw it (4) until it is tightened.

The function of each switch on the hydraulic function control panel is described below.

MOVEMENT CONTROL CONNECTOR Section movement / AUX switch opening Opening 1 ÷ 4 A Closing 1 ÷ 4 C 1 - 4 Opening AA Boom height

Closing

Opening

Closing

Opening

Closing

# • Connect the connector marked with "DD" to the pilot valve, and then the other connectors, as specified on the table:

### 9.4 Connection of sensors and other available functions

Fix the connectors to the relevant functions according to the initials indicated in your assembly general diagram (par. 7.1).

Harness cables are marked with a symbol denoting their functions: please see the table for correct harness connection.

# Use ARAG sensors: use of unsuitable sensors not provided by ARAG automatically voids the warranty.

 $igstar{}$  ARAG is not liable for damage to the equipment, persons or animals caused by failure to observe the above instructions.

ITEM	CONNECTION
F	Flowmeter
м	Pressure sensor
R	Foam marker
S	Speed sensor
х	Level sensor
Р	Control valve
G	Main valve

- The products are supplied with the sensor installation instructions.

- Connection of:
- flowmeter;
- pressure sensor;
- level sensor
- foam marker.

All ARAG sensors use the same type of connector. Connect the sensor connector to the relevant harness; make sure it is correctly fitted and push it until locking it.



# 9.5 Pen drive

The pen drive may be used to exchange data with the BRAVO 180S computer.





#### SETUP 10

#### 10.1 Computer switching on/off













SETUP







# 11 ADVANCED SETUP

The computer can be set-up with the all data required to ensure a correct distribution of the treatment product. This operation must be done once only, **when installing the computer**.

### 11.1 Tests and checks before programming

### Before computer setup, check:

- that all components are correctly installed (control unit and sensors);
- $! \Delta$  the correct connection to the power source;
  - the component connection (main control unit and sensors).

Failure to correctly connect system components or to use specified components might damage the device or its components.



The screens indicated in the following paragraphs refer to setup key-points only; The display could change when pressing the keys described in the text.

When setting the data, the relevant value blinks on the display.



#### 11.2 Language



#### 11.3 Units of measur.

EU



Set the units of measurement used for Bravo 180S.

> EU (I/h, km/h, bar) US (GPA, mil/h, PSI) US TURF (applied volume = gal / 1000 square feet, mil/h, PSI)

#### 11.4 No. of sections

Fig. 29



#### 11.5 Total boom width

This parameter represents the nozzle actual spraying range on the ground: for example, by positioning 8 nozzles at a distance of 50 cm one from the other, the boom section width to be set is 4.00 m.

The displayed value (Fig. 31) represents the sum of the section width values, therefore to change the parameter it is necessary to set the width of each boom section: the sum of the width values will be re-calculated automatically.

1 After selecting the menu Total boom width, press DK to gain access to the sub-menu to select / modify the single sections.

2 Use the keys to scroll the sections in the sub-menu Section until viewing the section to be modified: the section number is indicated on the top right side of the display, whereas the first line shows the current value (Fig. 32).

3 Press **DK** to confirm the access to the modification function.

4 Enter the section width value and repeat the setting procedure for each section.



### 11.6



Enable / disable the variable application rate.

No > Yes

With option Ves, the computer is preset to select the application rate Variable when setting the jobs (par. 12.1).

Fig. 34

Shifting of the cursor		Menu item scrolling or Data increase/decrease	

Confirms access to menu or data change





ロк



### 11.7 Speed sensor



In this menu carry out all settings to calculate the speed.

Usually the computer calculates the information concerning the speed thanks to pulses received by the sensor installed on the wheel.

If a GPS receiver is directly connected to the Bravo 180S, this menu allows selecting the receiver as alternative source to the wheel sensor, and so to receive in real time the speed data provided by the GPS.

After selecting the menu Speed sensor, press DK to access the sub-menus.

### > Wheel

This parameter is used by the BRAVO 180S computer to calculate the vehicle driving speed and, according to this, the instantaneous application rate. The wheel constant relates to the type of wheel being used and the number of detection points of the sensor installed on it. BRAVO 180S can save 3 different wheel constants.

### In case of replacement of the wheel featuring the detection points of the speed sensors, the wheel constant can change. In this case it is necessary to set the parameter again.

- 1 Select the wheel type (3 types available).
- 2 Press CK. The constant can be entered with two different procedures (Manual setup or Automatic calc.), described below.
- **3** Select the desired procedure and press  $\Box \kappa$  to enter the constant.



Menu item scrolling or Data increase/decrease



















### 11.11 Pressure sensor



11.12 Flow calculation \*



11.13 Pressure calculation \*



11.14 Nozzle quantity \*



11.15 Tank source



#### Tank Setup 11.16



(menu Tank profile > Save on page 24).

Shifting of the cursor

Menu item scrolling or Data increase/decrease

Confirms access to menu Пκ or data change

Fer







### 11.17 Spraying Menu

# Spraying Menu Large

Fig. 54

Data	extended	short
Speed	•	•
Pressure**	•	•
Flowrate	•	٠
Surface	•	•
Sprayed fl.	•	•
Tank level	•	
Time	•	
Distance	•	

Upon spraying it is possible to display and check in real time the current spraying data. BRAVO 180S can display such data in extended or short mode.

The table indicates the two display modes:



Press. calc.

par. 11.13





Confirms access to menu or data change





#### **USER SETTING** 12

Before starting a treatment, some settings are necessary for a correct job. Once all necessary data have been set, it is possible to immediately start spraying.

# ACCESS TO THE USER MENU





The screens indicated in the following paragraphs refer to setup key-points only. The display could change when pressing the keys described in the text.

When setting the data, the relevant value blinks on the display.



Shifting











In this menu it is possible to set 10 different types of treatments.









#### 12.2 Nozzle data \*

This menu allows setting and viewing the values of the nozzles being used.



Nozzle type	Unit of me E	asurement U	Unit of measurement US - US TURF		
ISO	Flowrate (I/min)	Pressure (bar)	Flowrate (GPM)	Pressure (PSI)	
ISO Orange	0.40	3.00	0.100	40	
ISO Green	0.60	3.00	0.150	40	
ISO Yellow	0.80	3.00	0.200	40	
ISO Lilac	1.00	3.00	0.250	40	
ISO Blue	1.20	3.00	0.300	40	
ISO Red	1.60	3.00	0.400	40	
ISO Brown	2.00	3.00	0.500	40	
ISO Gray	2.40	3.00	0.600	40	
ISO White	3.20	3.00	0.800	40	
ISO Light blue	4.00	3.00	1.000	40	
ISO Light green	6.00	3.00	1.500	40	
ISO Black	8.00	3.00	2.000	40	

Nozzle type	Unit of me E	asurement U	Unit of measurement US - US TURF				
USR (USER)	Flowrate (I/min)	Pressure (bar)	Flowrate (GPM)	Pressure (PSI)			
Туре А	1.00	3.00	0.264	40			
Туре В	2.00	3.00	0.528	40			
Type C	3.00	3.00	0.793	40			
Type D	4.00	3.00	1.057	40			
Type E	5.00	3.00	1.321	40			

\* MENU VISIBLE ONLY WITH SPECIFIC SETTINGS: TO VIEW IT, ENABLE ONE OF THE INDICATED OPTIONS. Flow calculation > Pressure sensor par. 11.12 **V** par. 11.13 Press. calc.















1.00

Rate correction

Set the density factor of the sprayed fluid.

MN Flowmeters of the ORION series (code 462xxx) are not affected by the density difference of the fluids: set the factor to 1.00.





Shifting















Totalizers Export Fig.71	<ul> <li>there is a totalizer for each preset job (10 available), plus the "T00" one (that can not be reset) which includes all jobs performed by the device.</li> <li>the current job data are summed to the relevant totalizer each time you select a new job (par. 14.1).</li> <li>It is possible to save the totalizer reports on pendrive using the relevant function Export (Fig. 71).</li> <li>it is possible to delete all job data (par. 14.2).</li> </ul>
	TOTALIZER RECORD FILE
File name structure:	
T01-0003.RPT	• SAVING THE TOTALIZER ON PENDRIVE
Reference job Progressive number number Fig. 72 (01÷10)	- Select Export (Fig. 71) and press ロK. In the example of Fig. 72, Bravo 180S saves the <b>T01-0003.RPT</b> file on the pendrive. At each following saving the computer will increase the report number ( <b>T01-0004.RPT</b> , etc.)
Data in the file can be displayed on Pers	onal Computer with a text editor. Each file will contain the following data*:
Job's data	
Job No.: 01 [Active]Area: 0.000 haSprayed qty: 0 lTime: 00:00 hProductivity: 0.0 ha/hTarget rate: 300 l/haRate applied: 0 l/haNozzle type: ISO-BlueNozzle qty: 40Distance: 0.000 km	

\* These data represent just a mere example. In real facts they will always be different according to the type of treatment .

#### 12.11 Settings manag.

The Bravo 180S settings can be loaded or saved on pendrive so as to reconfigure the device if necessary, solve problems or configure another Bravo 180S without repeating all operations manually.

M Once installation is completed, and you checked machine correct operation, we recommend you to store the whole configuration onto pendrive.

To use the menu items inert the pendrive in the suitable slot (par. 7.2).

> Save	
	Allows saving the Bravo 180S configuration on the pendrive: then it will be possible to load it any time it is necessary to repeat the same settings.
Settings manag.	- Select Save (Fig. 73) and press □K; The confirmation message 0k SETUP.BIN is displayed once the saving process is completed. - Press ESC.
Ga Ve Fig. 73	Saving alarms: USB not found Pendrive not inserted. Error! Space available on pendrive is over: eliminate some files from the memory and try saving again. If the problems persist, please contact the service centre. File not found The SETUP.BIN configuration has not been saved on the pendrive.
> Load	
	Allows to select a configuration file saved on the pendrive and to set Bravo 180S again.
	WARNING: BY LOADING IN THE BRAVO 180S THE SETUP. BIN FILE SAVED ON THE PENDRIVE, ALL SETTINGS CARRIED OUT SO FAR WILL BE LOST.
Load	- Select Load (Fig. 74) and press DK; The confirmation message OK SETUP.BIN is displayed once the configuration process is completed. - Press ESC.
Fig. 74	USB not found
	Configuration alarm: pendrive not inserted.



Shifting



Menu item scrolling or Data increase/decrease

Confirms access to menu ロк or data change

Quits the menu or Esc the data change





#### TREATMENT PRELIMINARY SETTINGS 14

	SET	Par.
	Speed sensor	11.7
	Boom width	11.5
	Job setup	12.1
TO BE CARRIED OUT	Nozzle data	12.2
OF THE COMPUTER	Minimum regulation pressure	12.3
	Minimum speed	12.5
	Display contrast	12.8
	Save settings to pendrive	12.10
	Select the wheel type	12.4
	Flowrate correction factor	12.6
TO BE CARRIED OUT	Level correction factor	12.7
	Select the job program	14.1
	Reset the totalizers	14.2
	Tank filling	14.5.1

M After having carried out the indicated settings start the treatment selecting between MANUAL (par. 14.3.2) and AUTOMATIC (par. 14.3.1) modes.

#### 14.1 Selecting the job program (for automatic control only)

Before starting the treatment select the correct job, among those pre-set in the User Menu (Par. 12.1).



14.2 **Counters reset** 



Shifting

Confirms access to menu Ωк or data change



# 14.3 Application rate regulation

Bravo 180S regulates the chemical products output in two different ways.

Press the AUTD key to select the desired mode: the type of active regulation during the job will be displayed.

### 14.3.1 Automatic operation (*DEFAULT*)



## 14.4 Automatic closure of the main valve (through SKIPPER)

BRAVO 180S can automatically switch off main valve through SKIPPER: the navigator can autonomously manage valve opening and closing, thus preventing the overlapping of already-sprayed areas.

To use the automatic closure, connect SKIPPER to BRAVO 180S and carry out the AUTOMATIC operation procedure (par. 14.3.1): for further information, refer to the user's manual supplied with the SKIPPER satellite navigator.

W/wWARNING: automatic closing is NOT active during manual operation.



\* This menu item is displayed only if the EXTENDED view mode of the spraying menu is selected (par. 11.17).

Master OFF Tank level	<ul> <li>1 From the Spraying Menu, press until selecting Tank level.</li> <li>2 Press the keys at the same time to access the tank filling procedure.</li> <li>The filling will be managed in different ways according to the mode preset in the menu Tank source (par. 11.15). Possible options:</li> <li>Manual (3a)</li> <li>Level Sensor (3b)</li> </ul>
	TANK LEVEL - MANUAL MODE
Tank filling 1200 l Fig. 92	From point <b>2</b> pass to menu Tank filling BRAVO 180S displays the tank capacity: the value has been set in advanced setup. <b>3a</b> Set the real quantity of fluid filled in the tank. <b>4a</b> Press $\Box K$ to confirm the data. <b>What is not possible to set values higher than tank total capacity.</b>
	TANK LEVEL - LEVEL SENSOR MODE
Tank level Ø l	From point <b>2</b> pass to screen Tank level. <b>3b</b> Press to scroll through the items: Tank level BRAVO 180S displays the real quantity of fluid inside the tank, detected by the level sensor
Fig. 93	Filled qty Start the filling pump and stop it at the end of the filling procedure. When the level sensor is connected, the display shows the filling data in real time.

![](_page_35_Picture_0.jpeg)

# 15 MAINTENANCE / DIAGNOSTICS / REPAIRS

# 15.1 Operation errors

The indicated messages blink alternatively

![](_page_35_Figure_5.jpeg)

![](_page_35_Picture_6.jpeg)

Fig. 94			
Par.	JOB MODE	MESSAGE ON DISPLAY / CAUSE	REMEDY
13.2.2	MAN. + AUTO	Disable Main Main switch ON upon computer switching on	Move main switch downwards (position OFF).
13.2.2 14.3.1	AUTO	Machine stopped! Main switch ON with machine stopped	<ul><li>Start the farming machine.</li><li>Move main switch downwards (position OFF).</li></ul>
14.3.1	AUTO	Missing flow! Main switch ON with machine stopped but rate at zero	Start the pump and move the farming machine.
11.9 14.3.1	Αυτο	Slow down! The rate does not reach the value required for output	<ul><li>Decrease the farming machine speed.</li><li>Check that the flowmeter constant value has been set correctly.</li></ul>
11.9 14.3.1	Αυτο	Accellerate! The flowrate exceeds the value required for output	<ul><li>Increase the farming machine speed.</li><li>Check that the flowmeter constant value has been set correctly.</li></ul>
11.11 14.5	MAN. + AUTO	Check sensor! Faulty pressure values have been detected	• Check the pressure sensor status and make sure there is no residual pressure in the system.
7.2 11.16	MAN. + AUTO	USB not found The pendrive is not inserted correctly	• Turn off the computer and check the insertion of the pendrive.
	MAN. + AUTO	Error! • The pendrive is blocked • The pendrive has not free space	<ul> <li>Switch off the computer and release the pendrive.</li> <li>Space needed for new information: delete the unnecessary files from the pendrive.</li> </ul>
12.11	MAN. AUTO	File not found (SETUP.BIN) The computer configuration has not been saved	Save the data.
11.16	MAN. + AUTO	File not found (TANK.TKL) The tank configuration has not been saved	Save the data.
11.16 12.11	MAN. + AUTO	Wrong file • The file relevant to the computer configuration (SETUP_BIN) is faulty. • The file relevant to the tank configuration (TENKJKL) is faulty.	• Try to save the data again.
7.1 7.2	MAN. AUTO	GPS timeout • Wrong cable connection for receiver • The receiver connection cable is damaged • The receiver is damaged	<ul><li>Check connection to receiver.</li><li>Replace the cable.</li><li>Replace the receiver.</li></ul>

# 15.2 Troubleshooting

FAULT	CAUSE	REMEDY	
The display dags not switch on	No power supply	Check power supply connection (par. 8.2).	
The display does not switch on	Computer is OFF	Press the ON key.	
Valve controls take no effect	Valves not connected	Connect the connectors (par. 9.2).	
One valve does not open	No power supply to valve	Check valve electric connection and operation.	
	Wrong setup	Check the setup of the wheel constant (par. 11.7).	
The display no longer shows the speed	No signal coming from the speed sensor	Check connections to speed sensor (par. 9.4).	
The displayed speed is not precise	Wrong setup	Check the setup of the wheel constant (par. 11.7).	
		Check the setup of the boom width (par.11.5).	
		Check the setup of the flowmeter constant (par. 11.9).	
Output volume readout inaccurate	Wrong setup	• Check the setup of the wheel constant (par. 11.7).	
		• Check the setup of the section valve type (par. 11.8).	
		Check connections to speed sensor (par. 9.4).	
		Check the setup of the boom width (par. 11.5).	
Covered area count displayed does not match	Wrong setup	Check the setup of the wheel constant (par. 11.7).	
actual distance covered		Check connections to speed sensor (par. 9.4).	
	The totalizer has not been reset	• Reset the totalizer (par. 14.2).	
	Wrong actur	Check the setup of the wheel constant (par. 11.7).	
Distance traveled count displayed does not match actual distance covered	Wong setup	Check connections to speed sensor (par. 9.4).	
match actual distance covered	The totalizer has not been reset	Reset the totalizer (par. 14.2).	
	Wrong satur	Check the setup of the flowmeter constant (par. 11.9).	
Coroyed fluid count displayed doop not match	Wong setup	• Check the setup of the section valve type (par. 11.8).	
litres/gpm actually sprayed	Use of three-way section valves without setting calibrated backflows	Perform setting.	
	The totalizer has not been reset	Reset the totalizer (par. 14.2).	
	Wrang actur	Check application rate setup (par. 12.1).	
	Wong setup	Check the setup of the boom width (par. 11.5).	
the automatic operation	System not adequately sized to provide required	Check maximum pressure valve adjustment.	
	rate	Make sure control valve is adequate for specific system.	
	Control valve malfunction	Check valve operation.	
	Wrong setup	Check full scale setup for pressure sensor (par. 11.11).	
Instantanoous prossure readout inacourate	Wong setup	• Check the settings of the nozzles being used (par. 12.1 - 11.14 - 11.5).	
Instantaneous pressure readout macculate	Pressure sensor not calibrated	Perform the calibration (par. 14.5).	
	Pressure sensor wrong installation	Check connections to pressure sensor (par. 9.4).	
	Wrong setup	Check pressure sensor setting (par. 11.11).	
Instantaneous pressure is not displayed	Computer does not receive signals from pressure sensor	• Check connections to pressure sensor (par. 9.4).	
	Pressure sensor wrong installation	Check connections to pressure sensor (par. 9.4).	
	Lovel concernet colliproted	• Perform the calibration (par. 11.16).	
The displayed tank level is not precise	Level sensor not calibrated	• Calibrate the level sensor again (par. 11.16).	
	Level sensor wrong installation	Check connections to level sensor (par. 9.4).	
	-	Check connections to the flowmeter (par. 9.4).	
During the tank calibration procedure, the	Wrong installation / no flowmeter installed.	• Install the flowmeter (par. 7.1).	
sprayed quantity is always steady on zero	Section valves and main control valve set to OFF.	• Take section valves and main control valve to ON (par. 13.2.2).	

# 15.3 Cleaning rules

- Clean only with a soft wet cloth.
- DO NOT use aggressive detergents or products.
- DO NOT clean equipment with direct water jets.

# 16 TECHNICAL DATA

<ul> <li>Advanced</li> </ul>	menu						
Data	Description		Min.	Max.	UoM	DEFAULT	Other values that can be set / Notes
Language	Display langu				English	English, Italian, Spanish, Portuguese, French, German, Polish, Croatian, Hungarian, Greek, Russian, Turkish, Czech.	
Units of measur.	Display unit o	f measurement				EU	US, US TURF
No. of sections	Number of se system	ction valves in the	1	7		5	
Total been width	Section 1 + 7		0.00	30.00	m	4.00	To view this value it is necessary to set the width of each
Iotal boom width	Section 1 - 7		0.0	100.0	ft	13.1	boom section
Variable rate	Application ra carried out th	te regulation rough Skipper				No	Yes
				99.99	EU: cm/pls	50.00	Number of constant to be set: 1 ÷ 3
Speed sensor	Wheel		Disabled	99.99	US - TURF: in/pls	19.68	Includes the sub-menus: Manual setup, Automatic calc.
	GPS source					No 2 Waya	Yes
	Section valves	5				Manual	2-Ways
Valves	Sections man	ag.				(P Mode)	Auto (M Mode)
	Regulation					3-Ways	2-Ways
	Main					3-Ways	2-Ways
Flowmotor	Orion	Orion					Data necessary to calculate the rate
Tiowifieter	Altro						Data necessary to calculate the fate
		Constant			EU: pls/l	600	
Flowmeter constant	Constant			30000	US - TURF: pls/gal	2271	Data necessary to calculate the rate
Procedure concer	Data necessa	Data necessary to determine the instantaneous pressure		1000.0	EU: bar	Disabled	
Pressure sensor	the instantane			14500	US - TURF: PSI	Disabled	
Flow calculation*	Sensor used t output	to calculate the				Flowmeter	Pressure sensor * Only if the pressure sensor is enabled
Press. calc.	Enabling/disa calculation	bling the pressure				No	Yes
Nozzle qty*	Number of nozzles on the boom		1	1000		40	* Only if "Yes" is set in the previous item (Pressure calc.).
Tank source	The active option affects the entire configuration of the Setup Cisterna			-	-	Manual	Level Sensor
			1	20000	EU: I	1000	
Tank settings	Manual	Tank volume	1	5500	US - TURF: gal	264	]
<u>-</u>				1000	EU:1	50	Below this value the computer triggers an acoustic and
		Tank reserve	No	264	US - TURF: gal	13	visual alarm
Spraying Menu	Allows selecting whether to view the totalizers					Large	Short

pls = pulse turn = turn

# • User menu

Data	Description	Min.	Max.	UoM	DEFAULT	Other values that can be set / Notes
			,	1		
	Select a job that can be set	1	10			-
	Rate Type				Constant	Variable, Disabled
Johs setun			6000	EU: I/ha		
	Target rate	Off	600	US - TURF: GPA		-
	Nozzle type				ISO	USR A ÷ E
	Nozzles type					Selection of nozzle to be set: ISO, USR
		0.01	99.99	EU: I/min	1.00	
Nozzle data	Flow	0.001	99.999	US - TURF: GPM	0.264	Value that each he medified ONEV for sustamined parallel
		0.00	999.9	EU : bar	3.0	Value that can be modified ONLY for customised nozzles
	Pressure	0	9999	US - TURF: PSI	44	
	Minimum prossure for	Disabled	100.0	EU: bar		
Min. reg. press.	automatic regulation block		1450	US - TURF: PSI	Disabled	-
Wheel selection	Selection of pre-set wheel	1	3			
	Below this set value the		99.9	EU: km/h		
Minimum speed	computer interrupts the spraying	Disabled	99.9	US - TURF: MPH	Disabled	
Rate correction	Fluid density factor	0.01	10.0		1.00	
Level correction		0.01	100.00	EU: kg/l	1.00	
	Fluid weight	0.01	1000.00	US - TURF: oz/gal	133.53	
Display contrast	Contrast adjustment	0	100	%	50	

# Output values

Data	Min.	Max.	UoM	Description	Notes	
	0	00000	EU: I/ba			
Volume applied	0.0	99999		Quantity of sprayed fluid for unit of	Shown on the first line of the display, during treatment	
	0.0	00000 00		surface	Shown on the instance of the display, during treatment	
-	0.00	199.9	EU: km/h			
Speed	0.0	199,9	US - US TURF: MPH	Vehicle driving speed		
Propouro	0.0	999,9	EU: bar		Present only if YES has been set in the advanced	
Flessule	0	9999	US: PSI		menu "Pressure calculation"	
Flow	0.0	999,9	EU: I/min	Fluid envoyed new time unit	Fluid actually anyound by the paralag	
FIOW	0.0	999,9	US - US TURF: GPM	Fluid sprayed per time unit	Fluid actually sprayed by the nozzles	
	0.000	999999	EU: ha		Electing point	
Area	0.000	999999	US: acres	Sprayed surface	The totalizer increases when the main switch is ON	
	0.000	999999	US TURF: 1000 square ft		The localizer increases when the main switch is ON	
Enroyed atu	0	999999	EU: I	Sproved fluid	The totalizer increases when the main switch is ON	
Sprayeu qiy	0	999999	US - US TURF: gal	Sprayed Iluid	The localizer increases when the main switch is ON	
	0	20000	EU: I		Electing point	
Tank level	0	5500	US - US TURF: gal	Remaining fluid in the tank	The totalizer decreases when the main switch is ON	
Time	00:00	10000	EU - US - US TURF: h	Treatment time	Floating point The totalizer increases when the main switch is ON From 00:01 to 99:59 the format is hh:mm	
Distance	0.000	99999	EU: km	Traveled distance	Floating point	
Distance	0.000	99999	US - US TURF: miles		The totalizer increases when the main switch is OFF	

## 16.1 Computer technical data

Description		
Display	Alphanumeric LCD 2 lines x 16 characters, backlit	
Power supply voltage	11 ÷ 14 Vdc	
Consumption (valves excluded)	150 mA	
Operating temperature	0°C ÷ 60 °C +32°F ÷ +140 °F	
Digital inputs	for open collector sensors: max 2000 imp/s	
Weight	800 g - Bravo without hydraulic controls 1140 g - Bravo with hydraulic controls (without harness)	
Protection against polarity inversion	•	
Protection against short-circuit	•	

![](_page_39_Picture_0.jpeg)

#### END OF LIFE DISPOSAL 17

Dispose of the system in compliance with the established legislation in the country of use.

#### 18 **GUARANTEE TERMS**

- 1. ARAG s.r.l. guarantees this apparatus for a period of 360 days (1 year) from the date of sale to the client user (date of the goods delivery note).
  - The components of the apparatus, that in the unappealable opinion of ARAG are faulty due to an original defect in the material or production process, will be repaired or replaced free of charge at the nearest Assistance Center operating at the moment the request for intervention is made. The following costs are excluded:
- disassembly and reassembly of the apparatus from the original system;
- transport of the apparatus to the Assistance Center.
- 2. The following are not covered by the guarantee:
- damage caused by transport (scratches, dents and similar);
- damage due to incorrect installation or to faults originating from insufficient or inadequate characteristics of the electrical system, or to alterations resulting from environmental, climatic
- or other conditions; damage due to the use of unsuitable chemical products, for spraying, watering, weedkilling or any other crop treatment, that may damage the apparatus;
- malfunctioning caused by negligence, mishandling, lack of know how, repairs or modifications carried out by unauthorized personnel;
- incorrect installation and regulation;
- damage or malfunction caused by the lack of ordinary maintenance, such as cleaning of filters, nozzles, etc.;
- anything that can be considered to be normal wear and tear.
- 3. Repairing the apparatus will be carried out within time limits compatible with the organizational needs of the Assistance Center. No guarantee conditions will be recognized for those units or components that have not been previously washed and cleaned to remove residue of the products used.
- 4. Repairs carried out under guarantee are guaranteed for one year (360 days) from the replacement or repair date.
- 5. ARAG will not recognize any further expressed or intended guarantees, apart from those listed here. No representative or retailer is authorized to take on any other responsibility relative to ARAG products. The period of the guarantees recognized by law, including the commercial guarantees and allowances for special purposes are limited, in length of time, to the validities given here.
- In no case will ARAG recognize loss of profits, either direct, indirect, special or subsequent to any damage.
- 6. The parts replaced under guarantee remain the property of ARAG.
- All safety information present in the sales documents regarding limits in use, performance and product characteristics must be transferred to the end user as a responsibility of the purchaser.
- 8. Any controversy must be presented to the Reggio Emilia Law Court.

![](_page_40_Picture_1.jpeg)

# Conformity Declaration (E

ARAG s.r.l. Via Palladio, 5/A 42048 Rubiera (RE) - Italy P.IVA 01801480359

Dichiara

che il prodotto descrizione: **Computer** 

modello: Bravo 180S serie: 46718xxxx

risponde ai requisiti di conformità contemplati nelle seguenti Direttive Europee:

# 2004/108/CE

(Compatibilità Elettromagnetica)

Riferimenti alle Norme Applicate:

# **UNI EN ISO 14982**

(Macchine agricole e forestali - Compatibilità elettromagnetica Metodi di prova e criteri di accettazione)

Rubiera, 22 aprile 2013

Giovanni Montorsi

(Presidente)

Only use genuine ARAG accessories or spare parts to make sure manufacturer guaranteed safety conditions are maintained in time. Always refer to ARAG spare parts catalogue.

![](_page_43_Picture_1.jpeg)

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